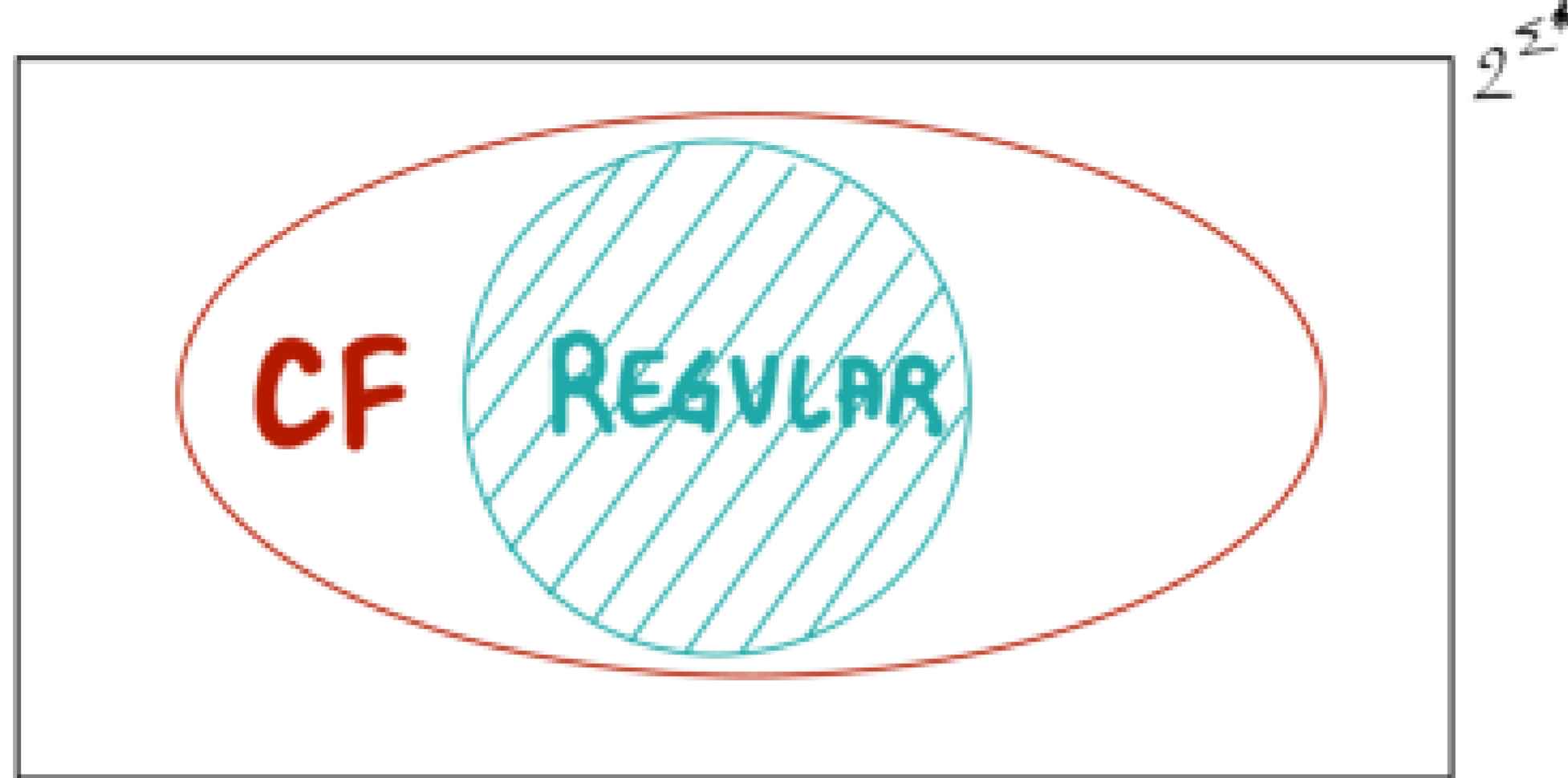


# TURING MACHINES

So far:



We saw operational characterizations of these language classes.

Regular : DFA/NFA : finitely many states, "one state memory"

Context-free : PDA : finitely many states, stack (LIFO)

$\{a^n b^n a^n \mid n \geq 0\}$  is not CF.

$\{ww \mid w \in \{a, b\}^*\}$  is not CF.

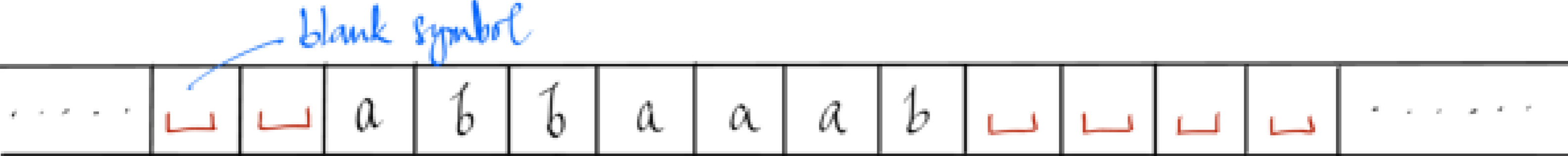
What can we add to a PDA to be able to recognize these?

A Turing machine is basically a finite-state automaton with a global tape. Each cell of the tape can contain a letter from a finite alphabet. Start out with the input string, and the rest of the tape is empty.

What can the machine do?

\* Read off the tape \* Write on the tape \* Move the head left or right

At each step, the head scans some cell of the tape, and the automaton is in some state, depending on which the automaton can move to some (other) state, the machine can write some new symbol on the tape cell, and move the head one cell to the left or to the right.



Set of states  
 input alphabet  
 tape alphabet  
 $\sqcup \notin \Sigma$   
 $\sqcup \in \Gamma, \Sigma \subseteq \Gamma$

A deterministic\* Turing Machine:  $M = (Q, \Sigma, \Gamma, \delta, s, t, r)$

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$$

current state  
 contents of current cell  
 new state  
 new contents of current cell  
 direction in which tape head should move

start state  
 accept state  
 reject state  
 $s, t, r \in Q$

$Q \setminus \{t, r\}$

DFA, but no outgoing transitions from  $t$  and  $r$

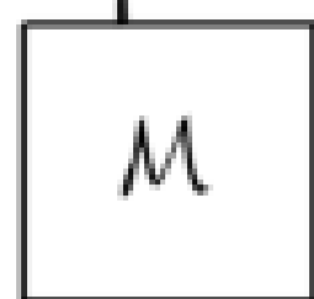
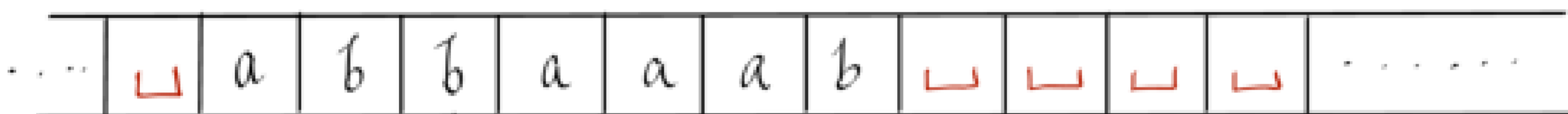
Input  $w_1 w_2 \dots w_n$ , each  $w_i \in \Sigma$   
 Written on  $n$  cells of the tape  
 The first blank signals the end of input.

As part of its operation, the following parameters change:

- current state
- current tape contents
- location of tape head

These form a configuration

$(ab, b, aab, q)$



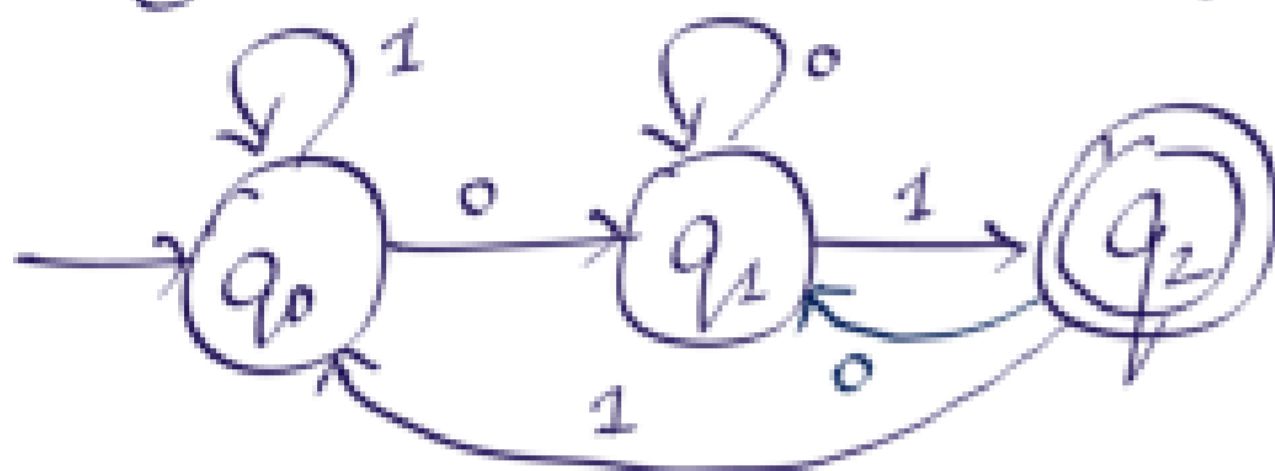
Suppose this is the current snapshot of my TM  $M$ , in state  $q$ .

We write the configuration as  $abqbaaab$ .

Formally, a configuration is  $uqv$ , where the machine is in state  $q$ , the current tape contents are  $uv$ ,  $u, v \in \Gamma^*$ , and the head points to the cell containing the first letter of  $v$ .

Example:

$$L = \{ \omega \mid \omega \text{ ends with } 01 \} \subseteq \{0,1\}^*$$



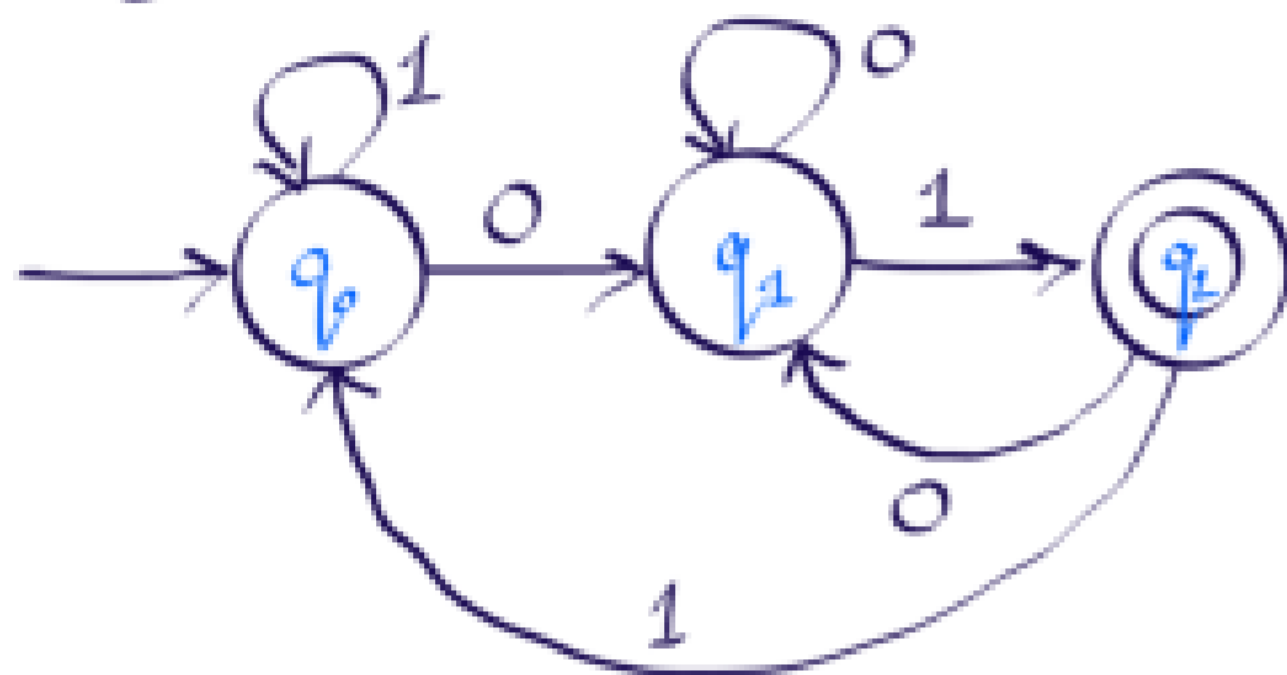
$$M = (Q, \Sigma, \Gamma, \delta, s, t, r)$$

$$\Sigma = \{0,1\} \quad \Gamma = \{0,1, \perp\}$$

$$s = q_0 \quad Q = \{q_0, q_1, q_2, t, r\}$$

Example:

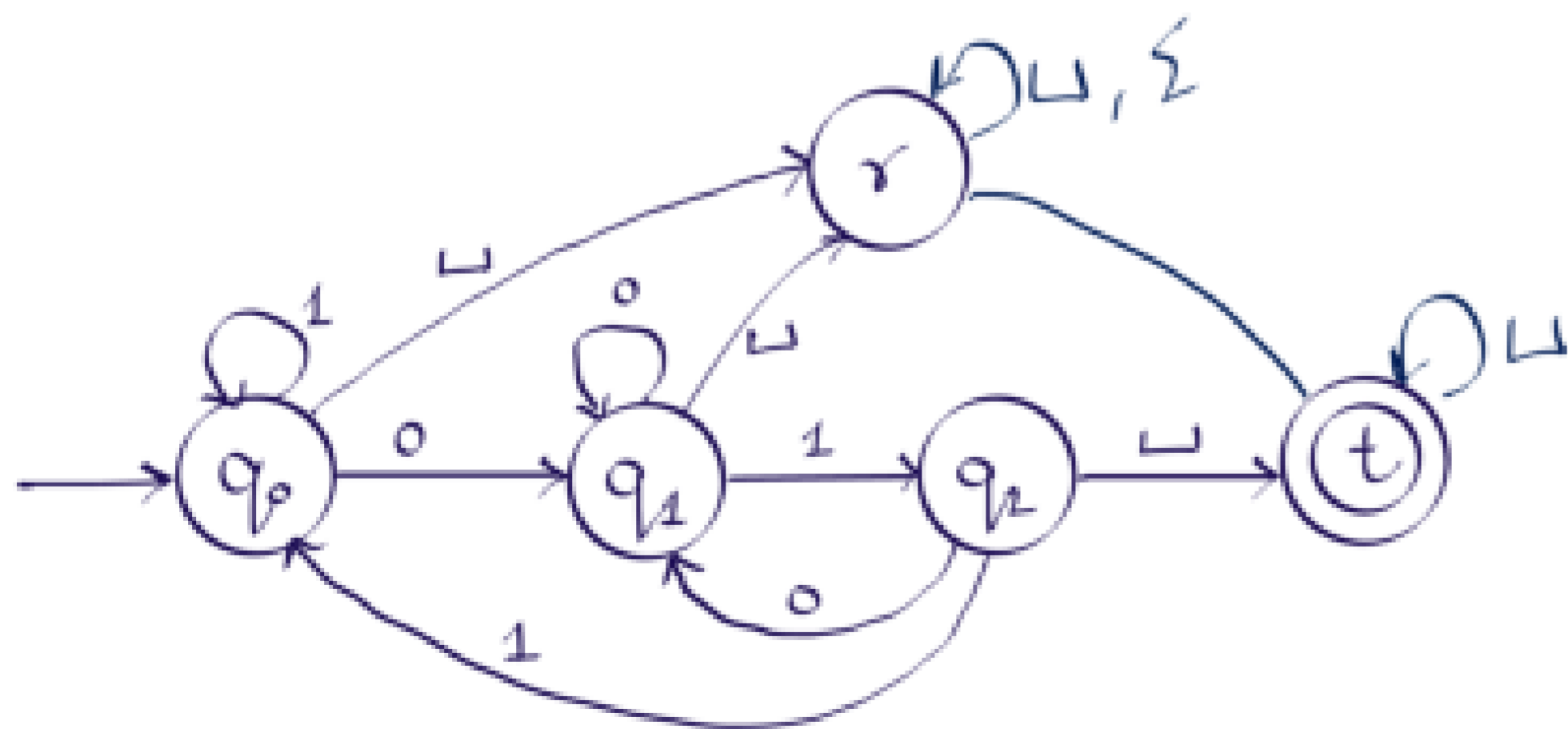
$L = \{ \omega \mid \omega \text{ ends with } 01 \} \in \{0,1\}^*$       $\Sigma = \{0,1\}$



$Q = \{q_0, q_1, q_2, t, r\}$

$\Gamma = \{0, 1, \sqcup\}$

$M = (Q, \Sigma, \Gamma, \delta, q_0, t, r)$

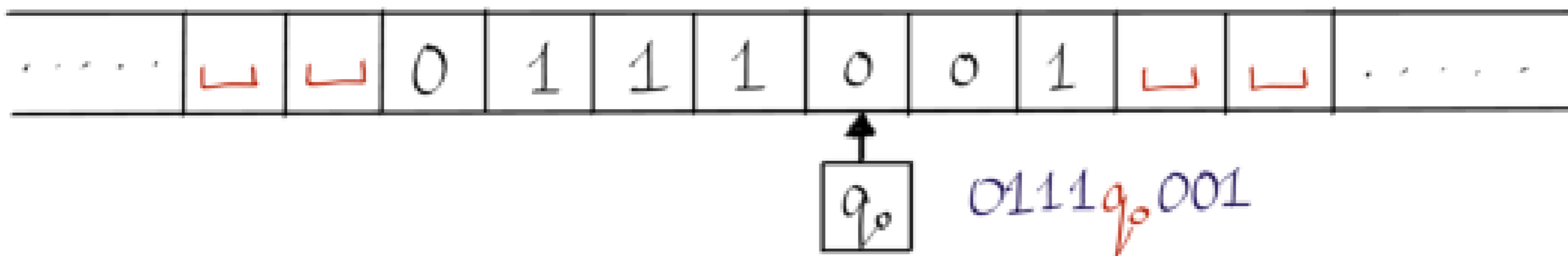
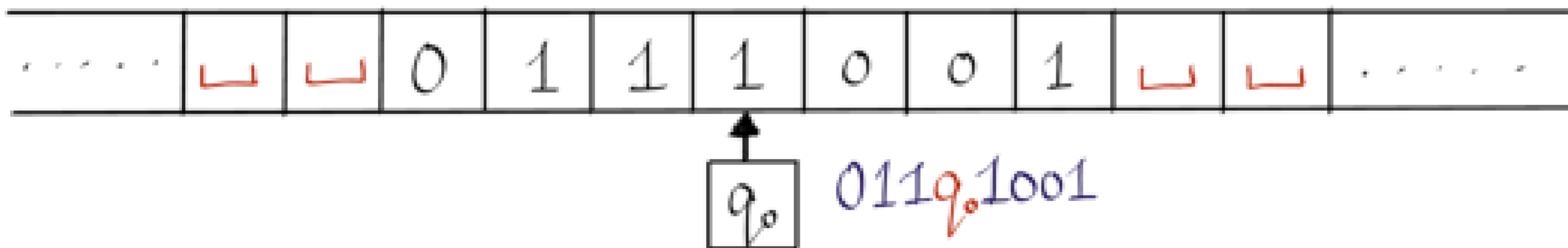
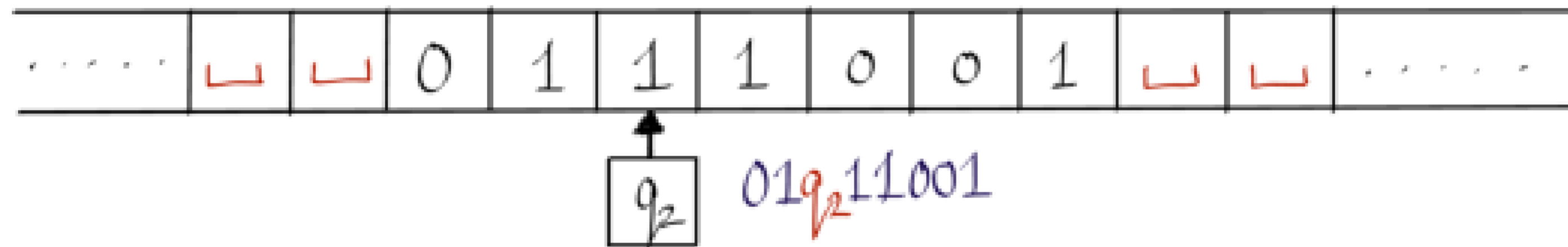
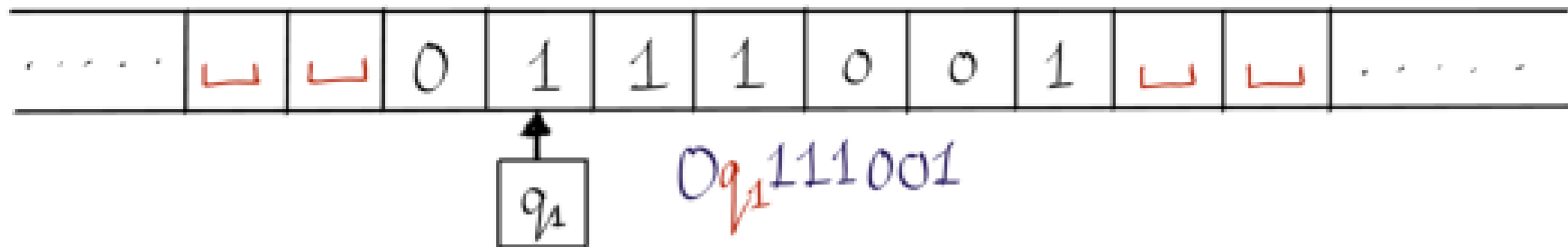
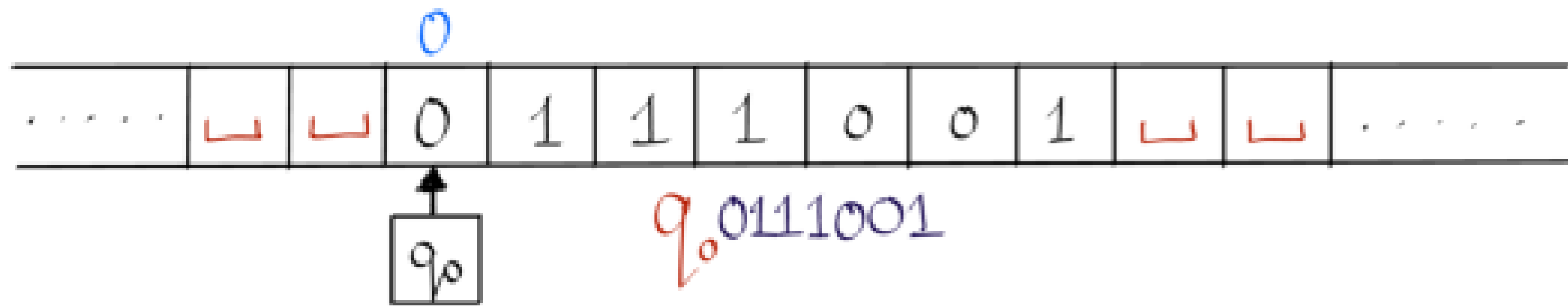


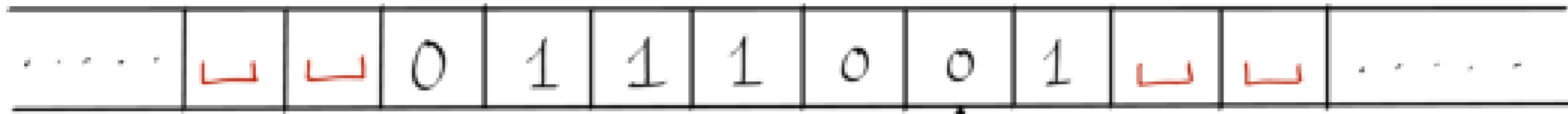
$\delta(q_0, 0) = (q_1, 0, R)$

$\delta(q_0, 1) = (q_0, 1, R)$

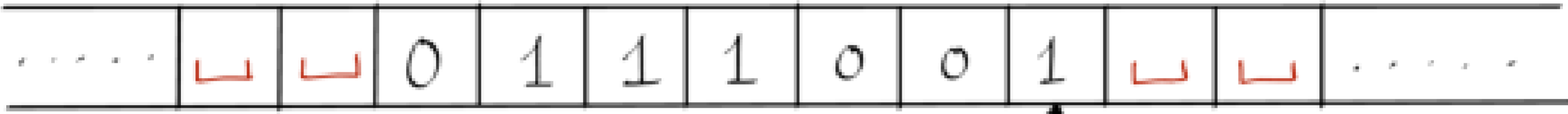
$\delta(q_1, 0) = (q_1, 0, R)$

$\delta(q_2, \sqcup) = (t, \sqcup, R)$

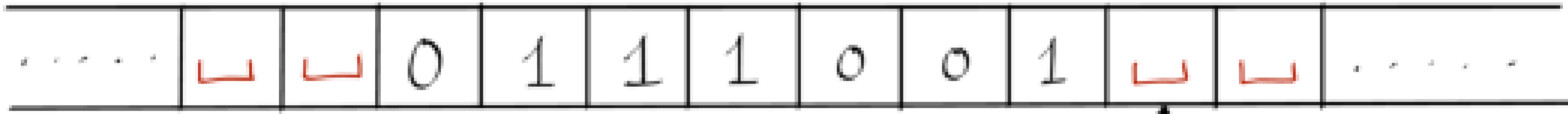




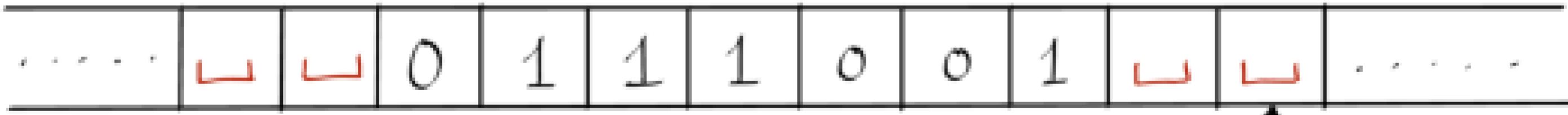
$q_1$ 
01110
 $q_1$ 
01



$q_2$ 
011100
 $q_1$ 
1



$q_2$ 
0111001
 $q_2$



$t$ 
0111001
┌
 $t$

Let  $u, v \in \Gamma^*$ , and  $a, b, c \in \Gamma$ . Then,

$u a q b v \xrightarrow{1} u a c q' v$  iff  $\delta(q, b) = (q', c, R)$ , and

$u a q b v \xrightarrow{1} u q' a c v$  iff  $\delta(q, b) = (q', c, L)$

The initial configuration is of the form  $s \omega$ , where  $\omega$  is the input.

$\omega$  is accepted by  $M$  if  $s \omega \xrightarrow{*} u t v$ , for some  $u, v \in \Gamma^*$ .  
accepting configuration

Similarly,

$\omega$  is rejected by  $M$  if  $s \omega \xrightarrow{*} u r v$ , for some  $u, v \in \Gamma^*$ .  
rejecting configuration

$M$  does not proceed beyond an accepting or a rejecting configuration.

A halting configuration is either an accepting or rejecting configuration.

$$\mathcal{L}(M) = \{ w \mid s w \xrightarrow{*}_M uv, \text{ for some } u, v \in \Gamma^* \}$$

$\mathcal{L}$  is Turing-recognizable if there exists a TM  $M$  s.t.  $\mathcal{L} = \mathcal{L}(M)$ .

What is the "language of a Turing machine"  $M = (Q, \Sigma, \Gamma, \delta, s, t, r)$ ?

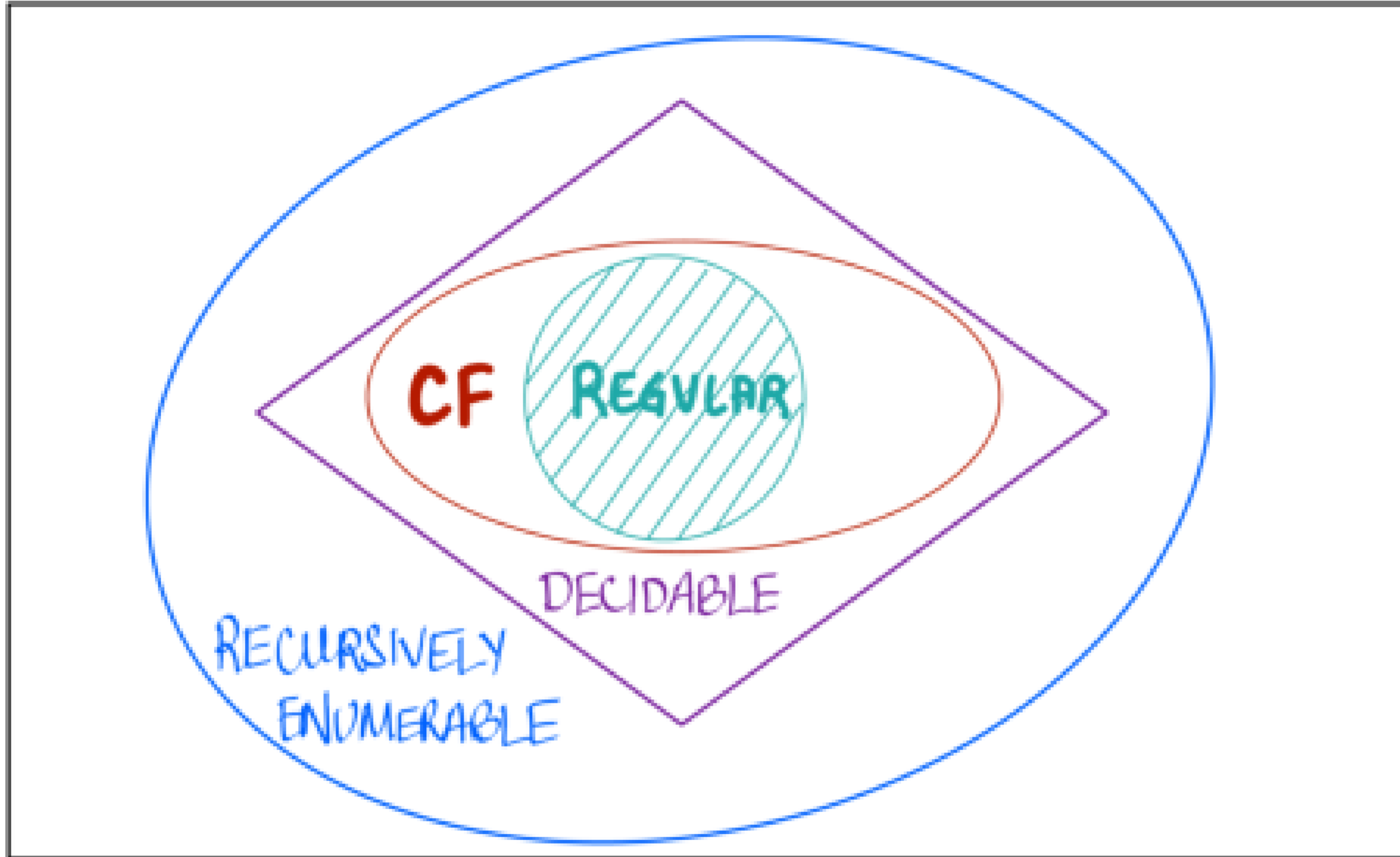
Consider  $P_M = \{ \omega \mid \text{there are } u, v \in \Gamma^* \text{ s.t. } s\omega \xrightarrow{*}_M utv \}$ , and

$N_M = \{ \omega \mid \text{there are } u, v \in \Gamma^* \text{ s.t. } s\omega \xrightarrow{*}_M uv \}$

Suppose  $\mathcal{L} = P_M$ . Then, we say that  $\mathcal{L}$  is *recognized* by  $M$ , and that  $\mathcal{L}$  is *Turing-recognizable*, or *recursively enumerable (r.e.)*

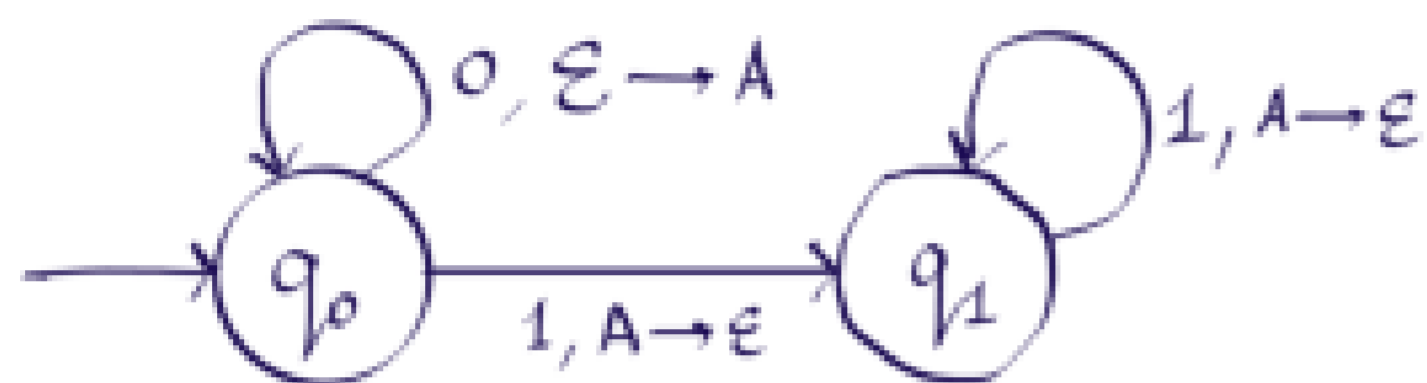
If  $\mathcal{L}$  is recognized by  $M$ , and in addition,  $N_M = \{0, 1\}^* \setminus P_M$ , then we say that  $\mathcal{L}$  is *decided* by  $M$ , and that  $\mathcal{L}$  is *decidable*, or *recursive*

Decidability  $\Rightarrow$  Turing-recognizability (but not the other way!)



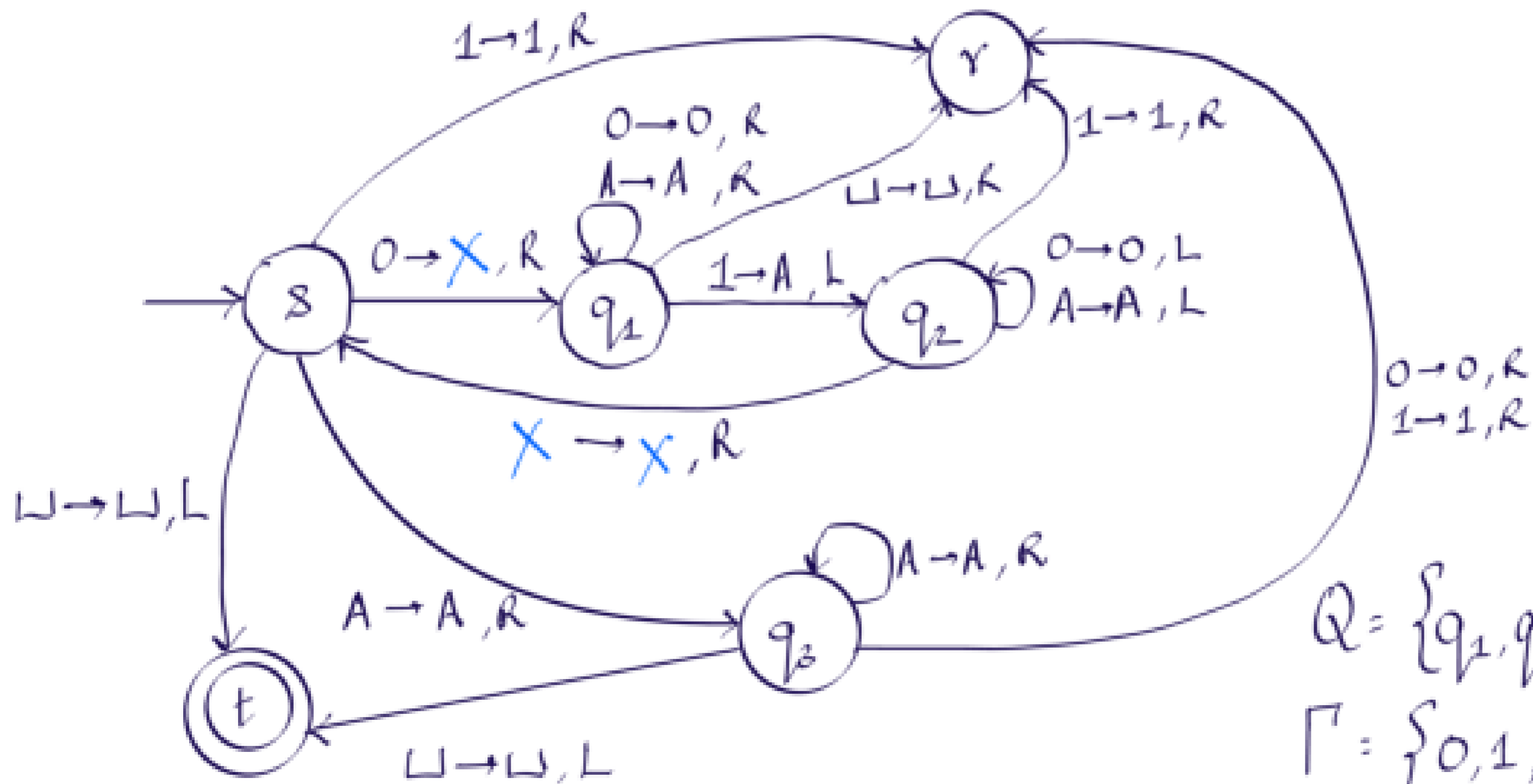
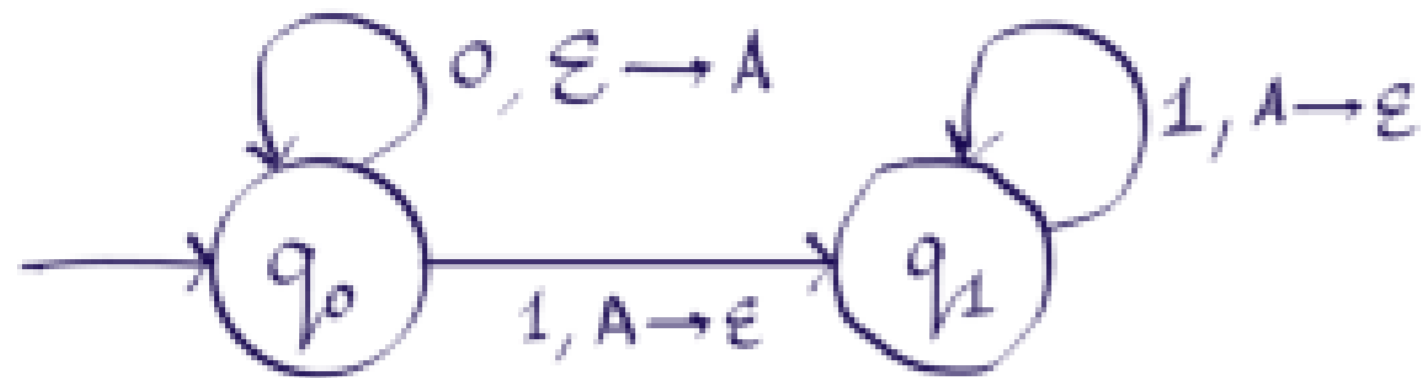
23\*

$$L = \{0^n 1^n \mid n \geq 0\}$$



$$M = (\{q_1, q_2, q_3\}, \{0, 1\}, \{0, 1, A\}, \delta, q_0, \emptyset)$$

$$L = \{0^n 1^n \mid n \geq 0\}$$



$$Q = \{q_1, q_2, q_3, s, t, r\}$$

$$\Gamma = \{0, 1, A, \sqcup, X\}$$